

PolyGen: An Autoregressive Generative Model of 3D Meshes

CSC2457 3D & Geometric Deep Learning

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Motivation and Main Problem

Generate Meshes with polygonal faces!

Have an Image?

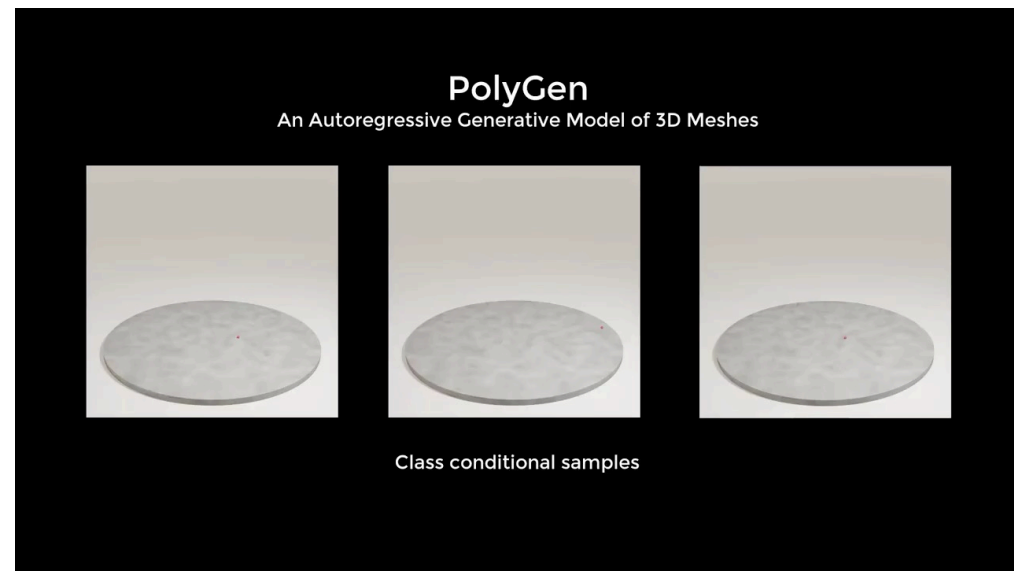
Have a class?

A Context?

Some vertices?

You can generate a mesh!

Think of the holodeck in Star Trek...

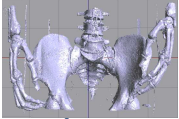


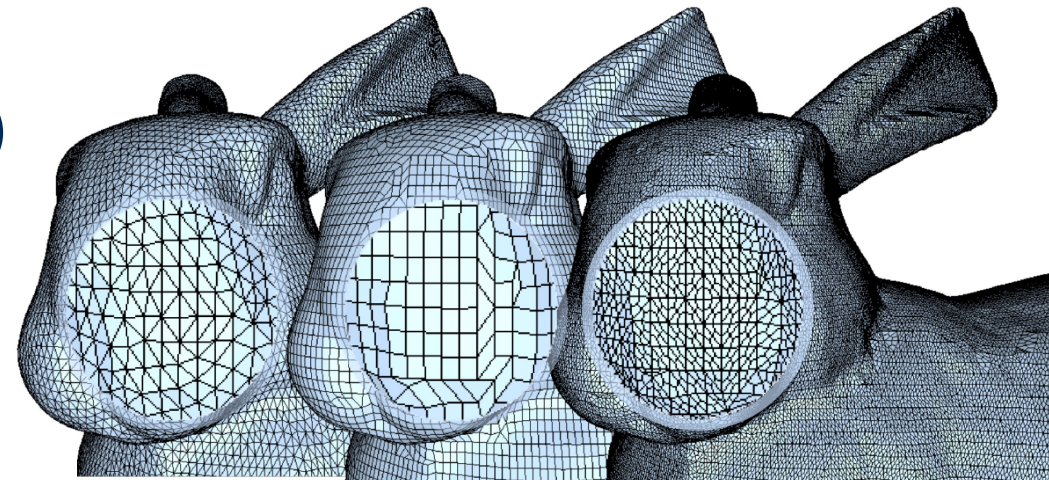
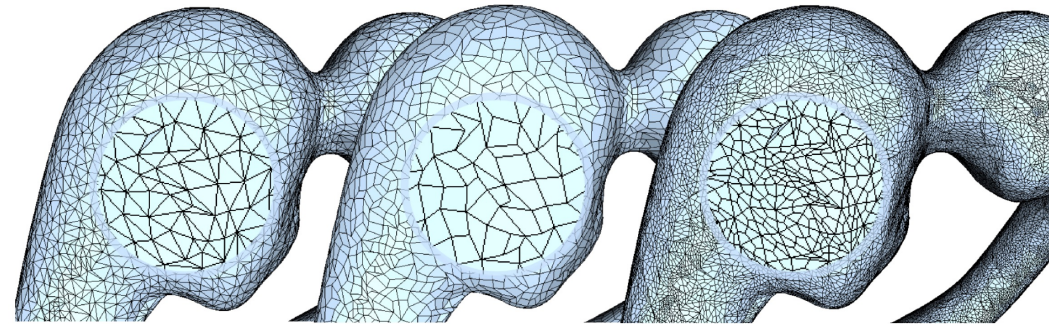
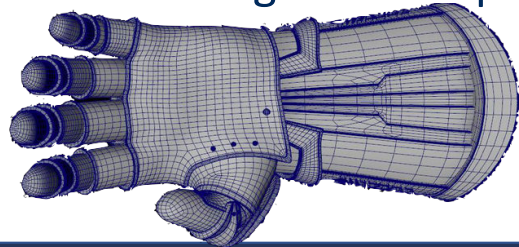
Motivation and Main Problem

- Why generative?
 - Synthesis – ‘novelty’
 - Repair
 - Vision & Reasoning
 - Environments for RL and other training
 - 3D Modeling
 - 3D Printing – sample the real world



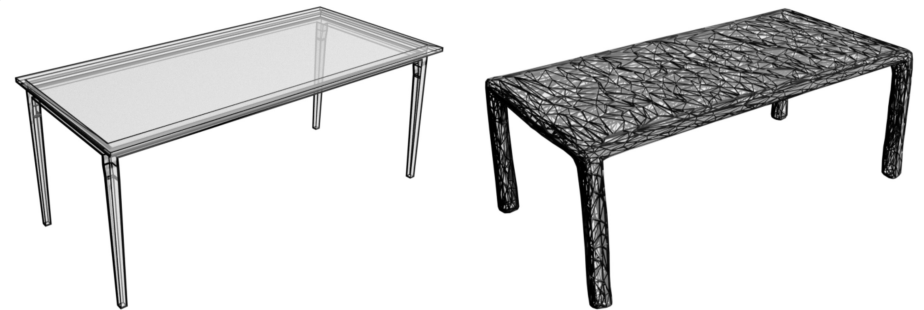
Why are generative meshes hard?

- Unordered elements
- Discrete face structure
 - N-gon means vary sequence size
- Triangle soup 
- Human meshes (games, graphics)
 - Compact
 - Good use of geometric primitives



Previous Work

- “...there were no existing methods that directly model mesh vertices and faces”
- Compression – yes – Draco (google)
- Ordered and unordered point clouds
 - The shape variational autoencoder: A deep generative model of part-segmented 3d objects - Nash & Williams 2017
 - Point cloud GAN – Li et. al 2019
 - Pointflow: 3d point cloud generation with continuous normalizing flows. Yang et. al 2019
 - PCT: Point Cloud Transformer. Guo 2020
- Voxels
 - A unified approach for single and multi- view 3d object reconstruction. Choy et.al 2016
 - Learning a probabilistic latent space of object shapes via 3d generative-adversarial modeling. Wu et. al 2016
 - Octree generating networks: Efficient convolutional architectures for high-resolution 3d outputs. Tarchenko et. al 2017
 - Unsupervised learning of 3d structure from images. 2016
- Functional representations: SDF, Implicits in general
 - Learning continuous signed distance functions for shape representation. Parks et.al 2019
 - Occupancy networks: Learning 3d reconstruction in function space. **Mescheder et. al. 2019**
- Parameterized deformable meshes
 - A papier-mâché approach to learning 3d surface generation **Groueix et.al. 2018**



PolyGen



Occupancy Networks (Mescheder 2019)



Implicit Representations – Gradient Fields (Cai 2020)



AtlasNet / Papier-mâché
(Groueix 2018)

Differences in approach

- Here, we directly model and generate meshes that are similar to those created by *people*
- Probabilistic model – yields diverse (creative?) output – robust to ambiguous input – principled
- Vertex model like PointGrow (Sun et al, 2020)
 - autoregressive decomposition to model point 3D clouds
 - Fixed length point clouds vs variable vertex sequences
 - Hand-crafted self-attention mechanism vs SOA deep architectures -> to model verts and faces – generation of high quality meshes

Contributions

- First: Unconditional mesh vertex & face models create n-gon meshes – directly, no post-processing! Autoregressive!
- Demonstrated conditional generation given any and/or only one of:
 - Object Class
 - Image
 - Voxels
- Application of Transformers to Meshes: vertex & face distributions, robust to bad input
- Output is diverse, realistic and directly usable in graphics applications – unlike previous post-processed output



General Background

PolyGen: An Autoregressive Generative Model of 3D Meshes

Charlie Nash¹ Yaroslav Ganin¹ S. M. Ali Eslami¹ Peter W. Battaglia¹

Generating Long Sequences with Sparse Transformers

Rewon Child¹ Scott Gray¹ Alec Radford¹ Ilya Sutskever¹



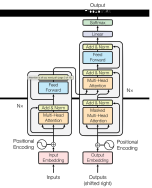
Pointer Networks

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Attention Is All You Need



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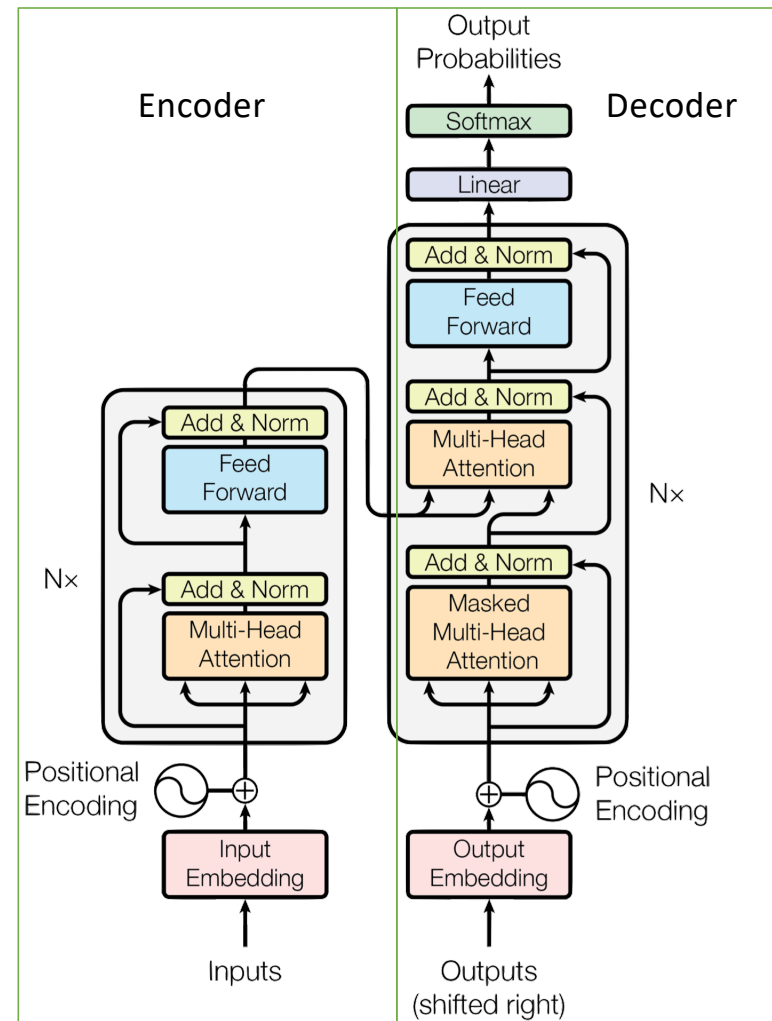
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General Background – Transformers & Attention



Why Transformers for Meshes?

- Short & Long range dependencies (context)
- Relationships between faces and vertices
 - Symmetries
 - Non-local dependencies
 - Arbitrary distributions
- Distribution over sequences
- Analogous to words / sentences / paragraphs
 - Autoregressive language models

Problem Setting

A mesh, \mathcal{M} has 3d vertices \mathcal{V} , which are indexed to form faces, \mathcal{F}

$$p(\mathcal{M}) = p(\mathcal{V}, \mathcal{F}) = p(\mathcal{F}|\mathcal{V})p(\mathcal{V})$$

$$\mathcal{F}_{\text{tri}} = \left\{ \left(f_1^{(i)}, f_2^{(i)}, f_3^{(i)} \right) \right\}_i$$

$$\mathcal{F}_{n\text{-gon}} = \left\{ \left(f_1^{(i)}, f_2^{(i)}, \dots, f_{N_i}^{(i)} \right) \right\}_i$$

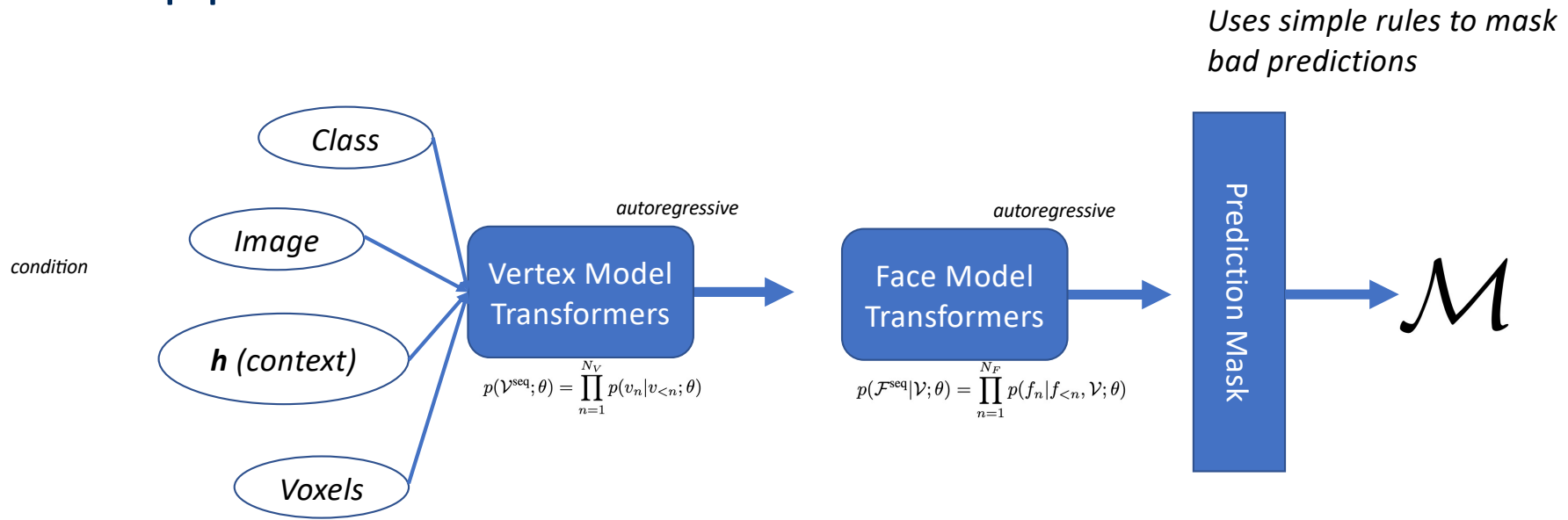
Problem Setting

A mesh, \mathcal{M} has 3d vertices \mathcal{V} , which are indexed to form faces, \mathcal{F}

$$\underbrace{\mathcal{V}^{\text{seq}} = v_n, n = 1, \dots, N_V}_{\text{8 bit-quantization (0-255)}} \quad p(\mathcal{V}^{\text{seq}}; \theta) = \prod_{n=1}^{N_V} p(v_n | v_{<n}; \theta) \quad \max(\log p(\mathcal{V}^{\text{seq}} | \theta))$$

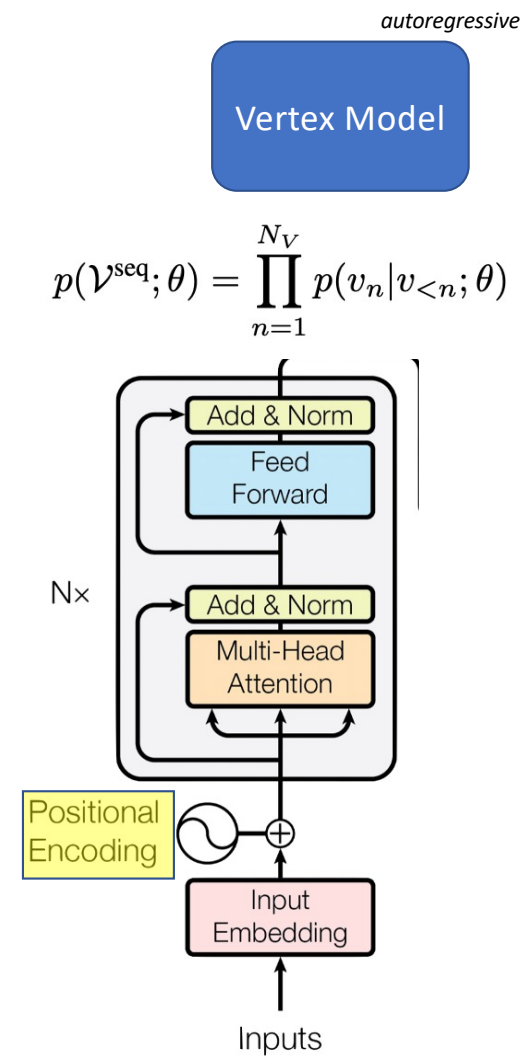
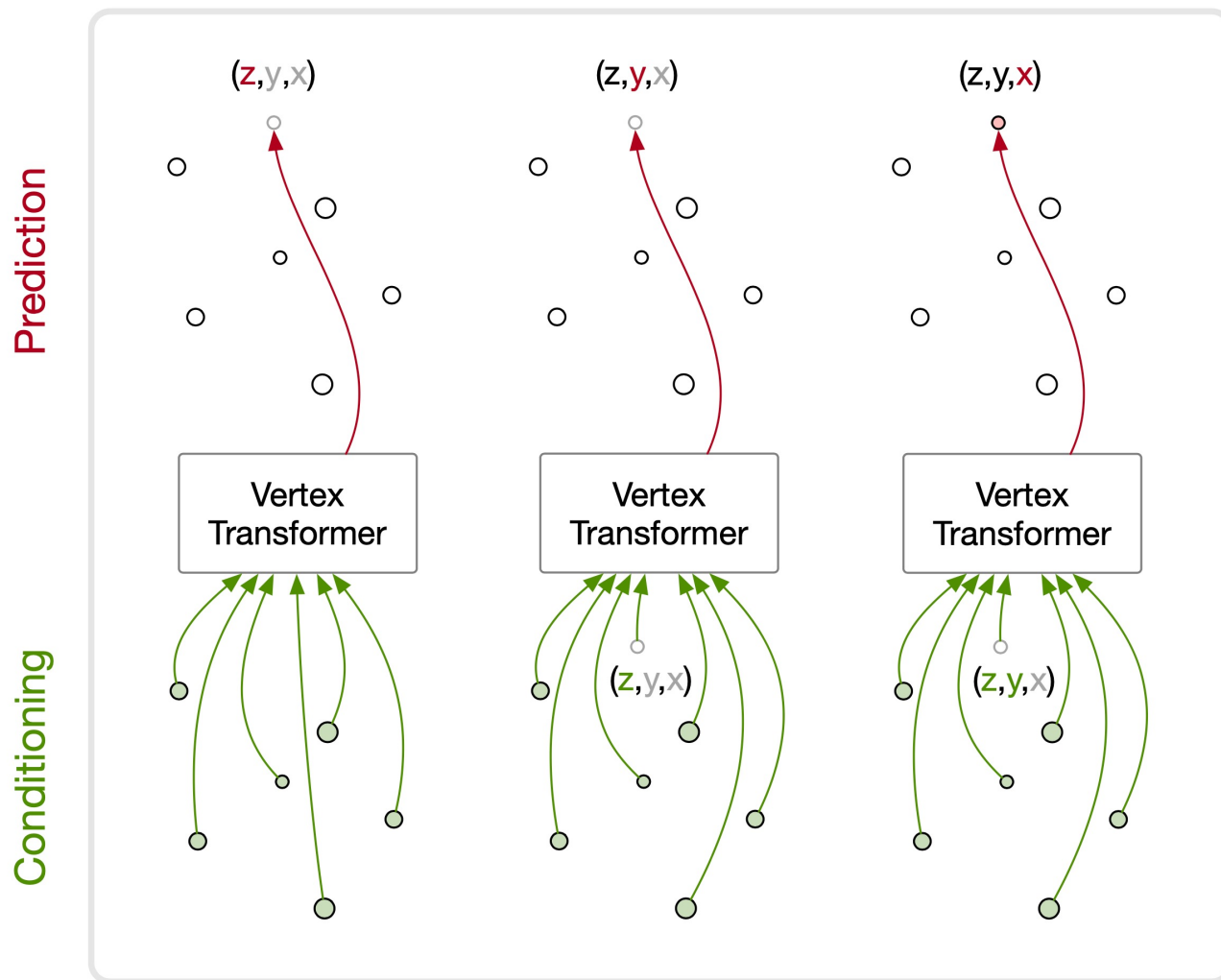
$$p(\mathcal{F}^{\text{seq}} | \mathcal{V}; \theta) = \prod_{n=1}^{N_F} p(f_n | f_{<n}, \mathcal{V}; \theta)$$

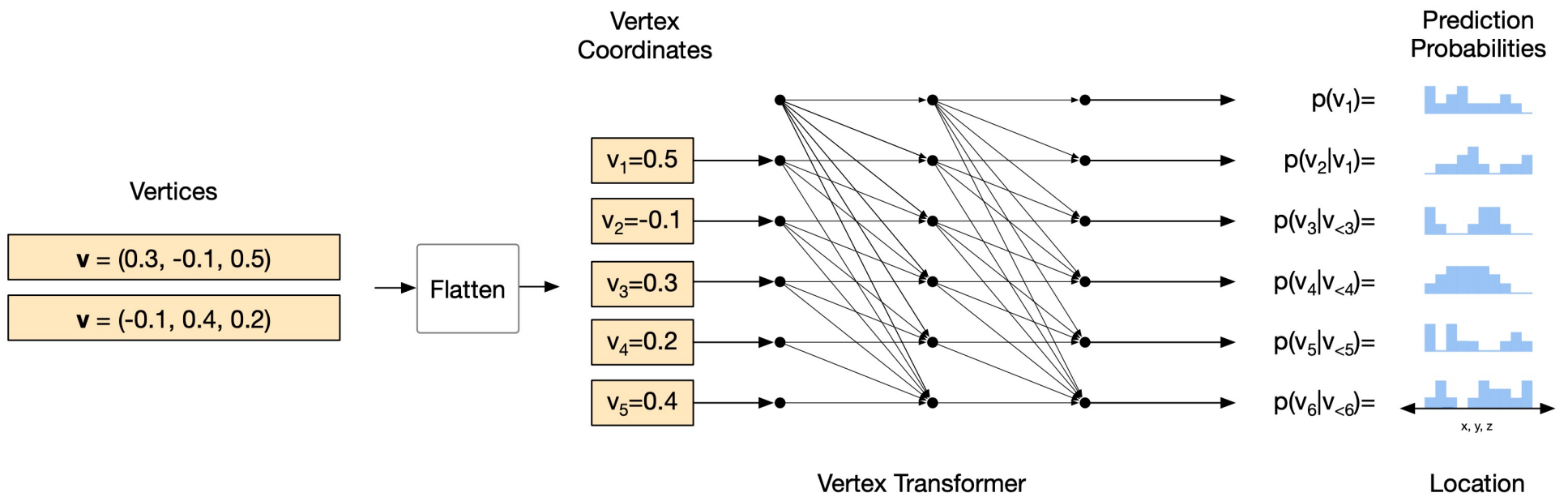
Approach



$$\mathcal{V}^{\text{seq}} = v_n, n = 1, \dots, N_V$$

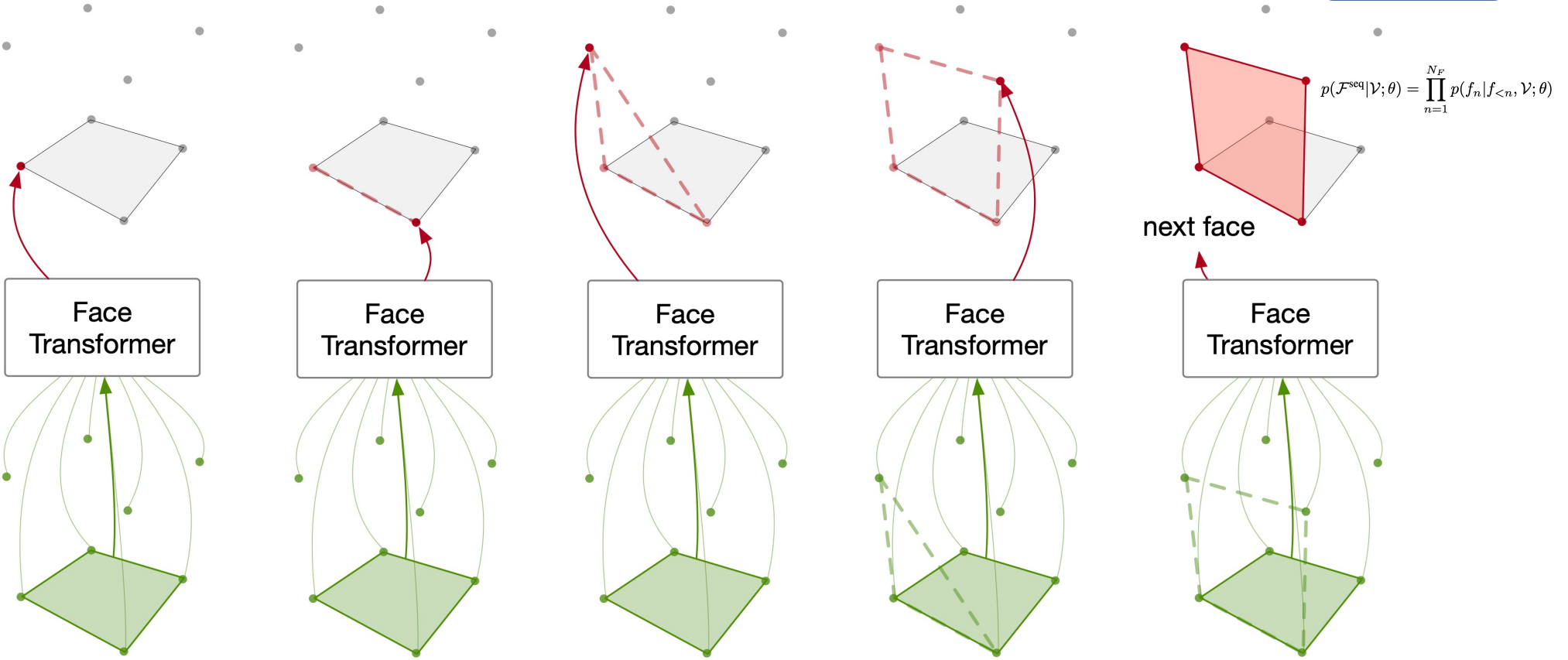
SHAPER-Net





autoregressive

Face Model



autoregressive

Face Model

Pointer Embedding $\mathbf{p}_n = D(f_{<n}, \mathcal{V}; \theta) : \{\mathbf{e}_v\}_{v=1}^{N_V} = E(\mathcal{V}; \theta)$

Vertex Embeddings

p

Vertex Scores

e_n

e_s

e_1

e_2

e_3

e_4

s_n

s_s

s_1

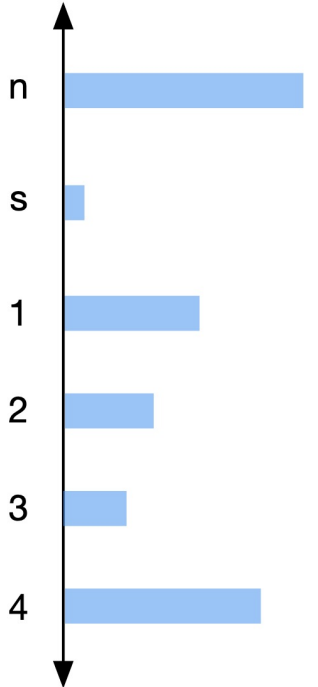
s_2

s_3

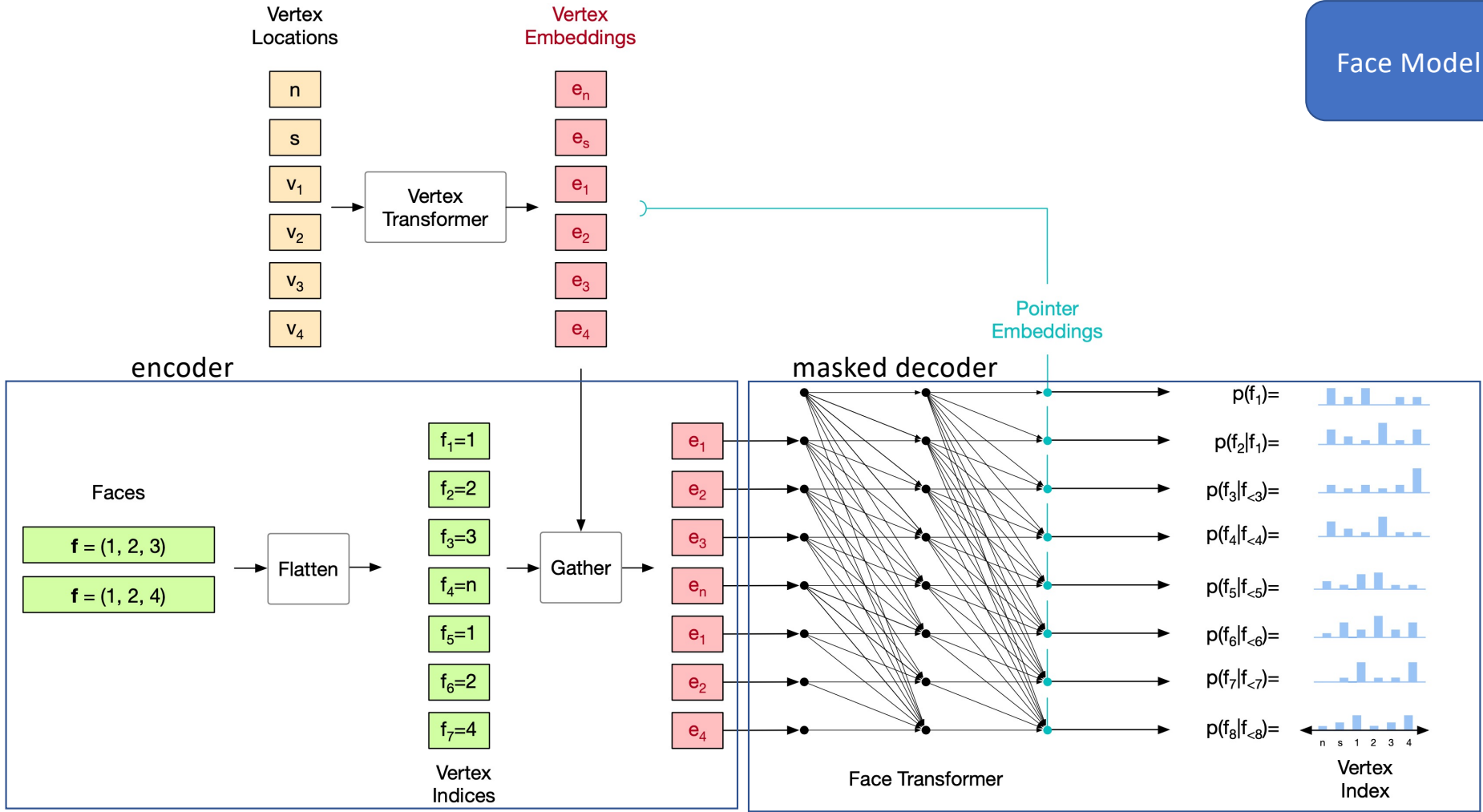
s_4

Dot Product

Softmax



Face Model



Discussion of results

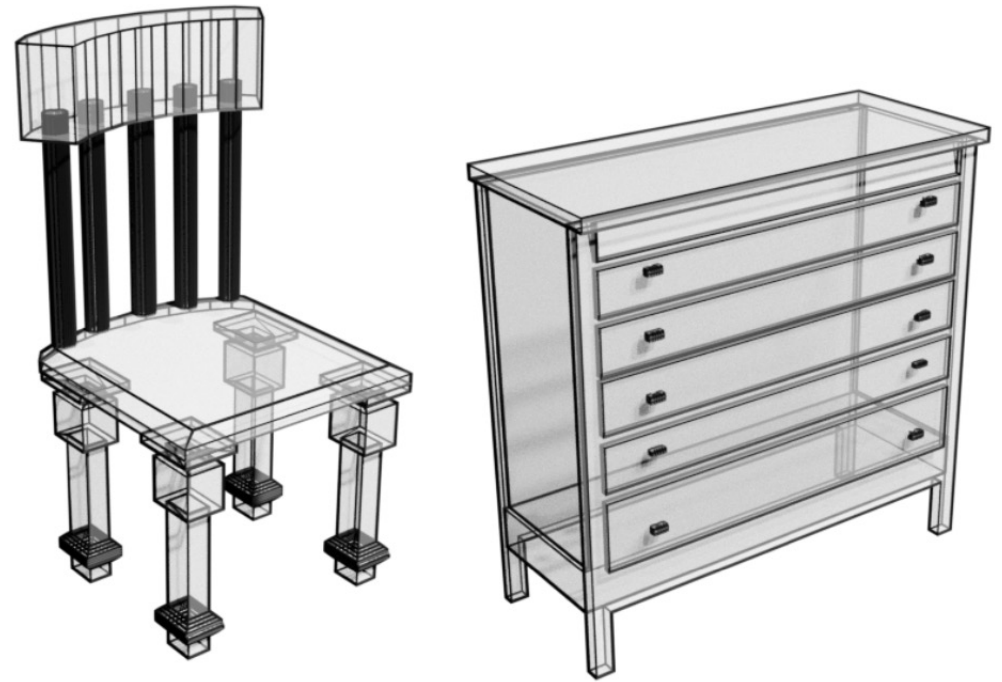
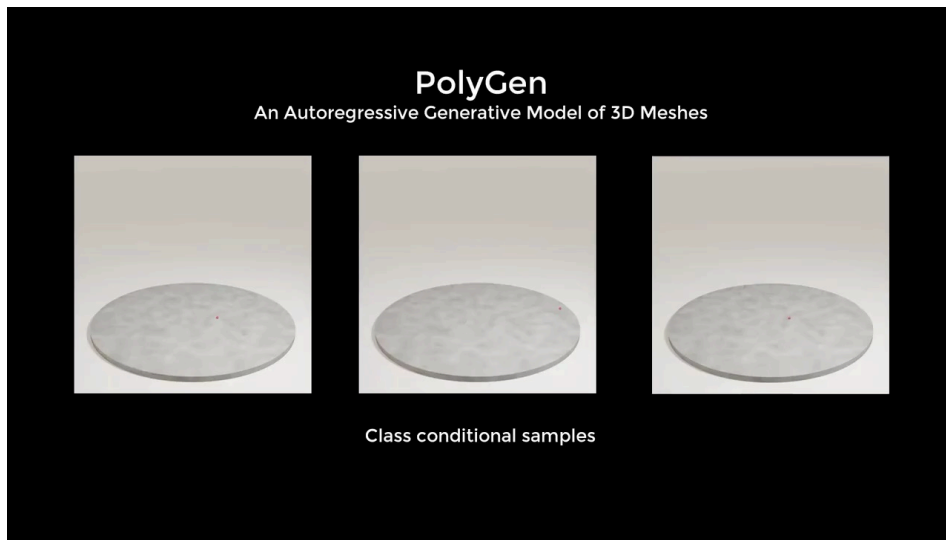


Figure 1. **Class conditional** n -gon meshes generated by PolyGen.

Discussion of results

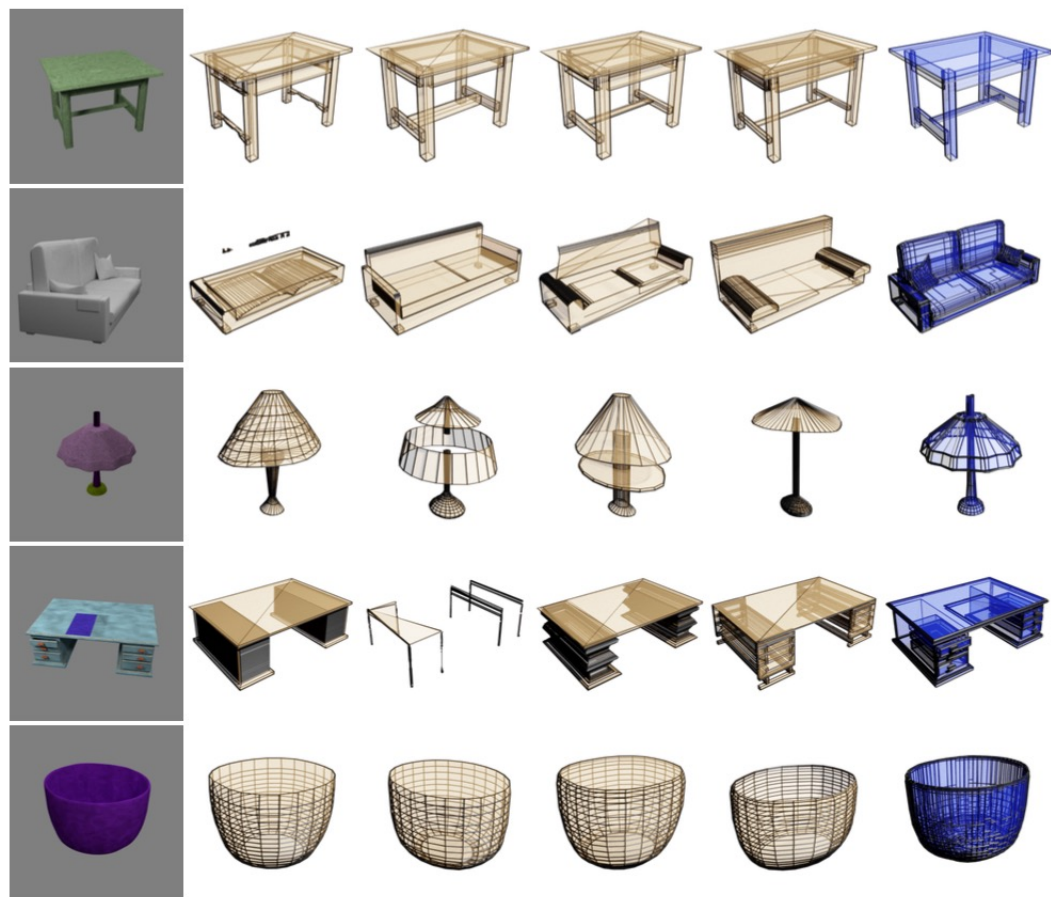
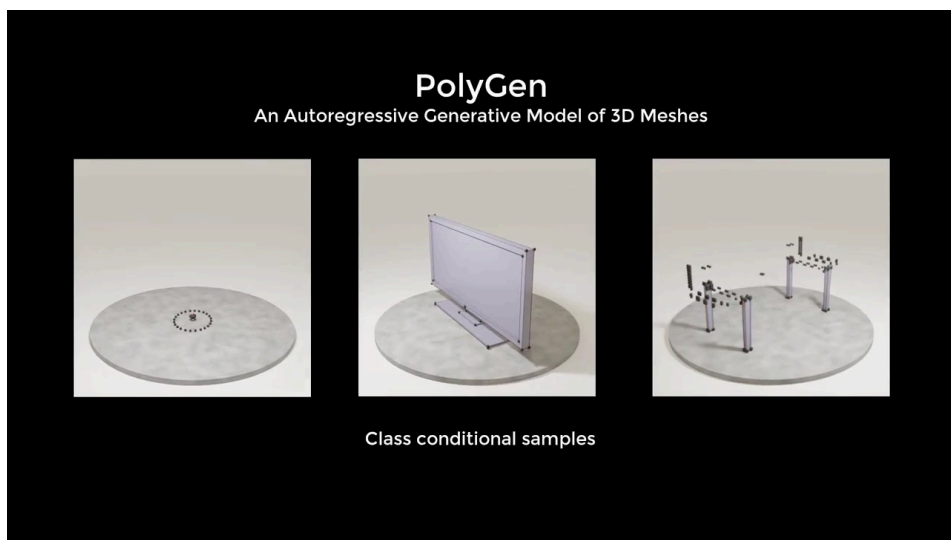


Figure 6. **Image conditional** samples (yellow) generated using nucleus sampling with top- $p=0.9$ and ground truth meshes (blue).

Discussion of results

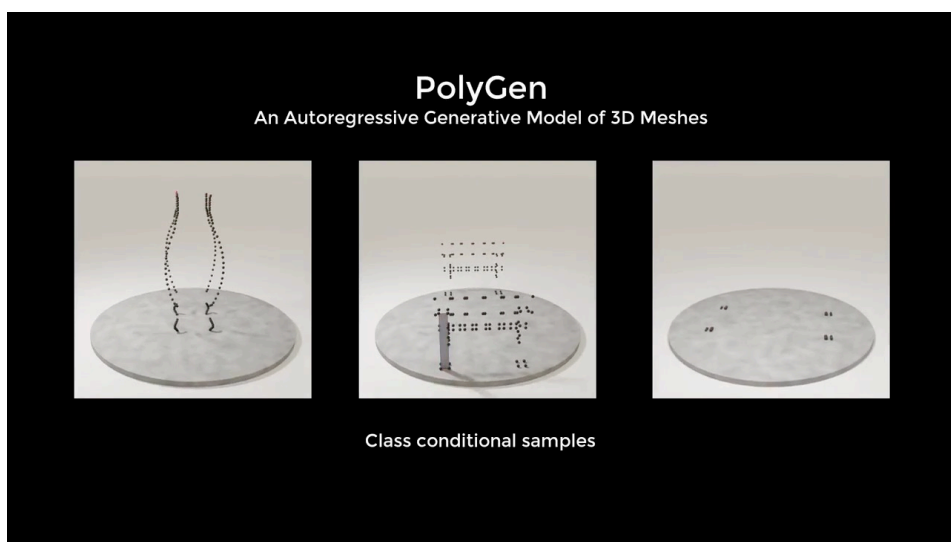


Figure 10. **Voxel conditional** (blue, left) samples generated using nucleus sampling with top- $p=0.9$ (yellow) and ground truth meshes (blue, right).

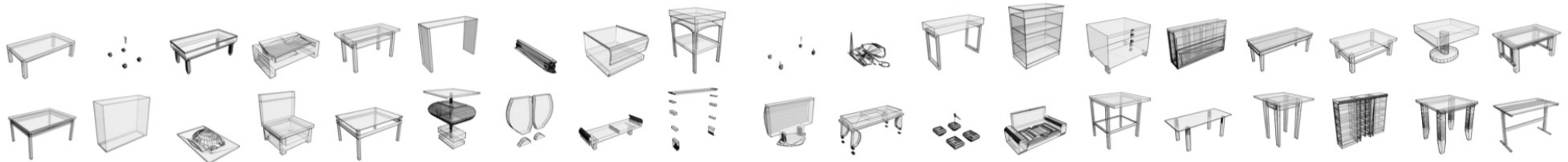
Experimental Results

Negative log-likelihood

- Mesh Generation

- Best model achieves:
 - log-likelihood 4.26 bits/vertex
 - 85% prediction for Vertices
 - 90% prediction for faces
- Accuracy of next vert coordinate & choice of vertex for next face
- No great metrics so...

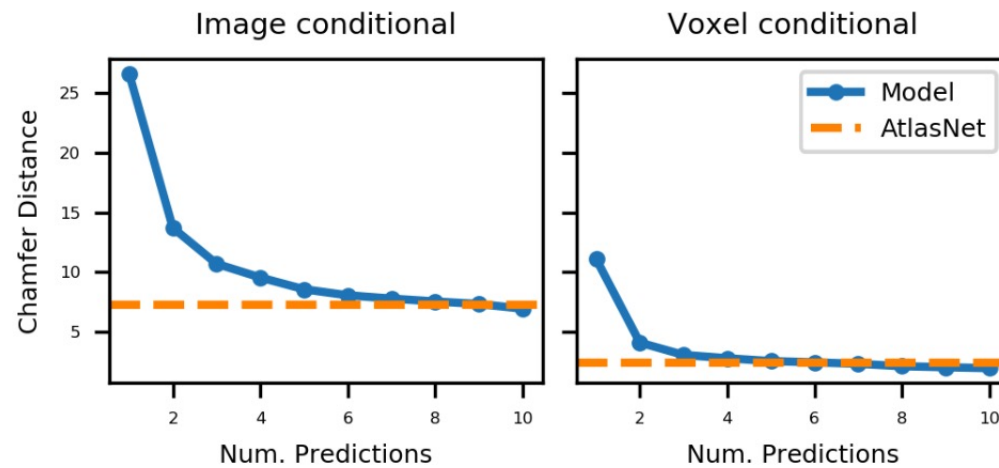
Model	Bits per vertex		Accuracy	
	Vertices	Faces	Vertices	Faces
Uniform	24.08	39.73	0.004	0.002
Valid predictions	21.41	25.79	0.009	0.038
Draco* (Google)	Total: 27.68		-	-
PolyGen	2.46	1.79	0.851	0.900
- valid predictions	2.47	1.82	0.851	0.900
- discr. embed. (V)	2.56	-	0.844	-
- data augmentation	3.39	2.52	0.803	0.868
+ cross attention (F)	-	1.87	-	0.899



Experimental Results vs. Mesh Reconstruction

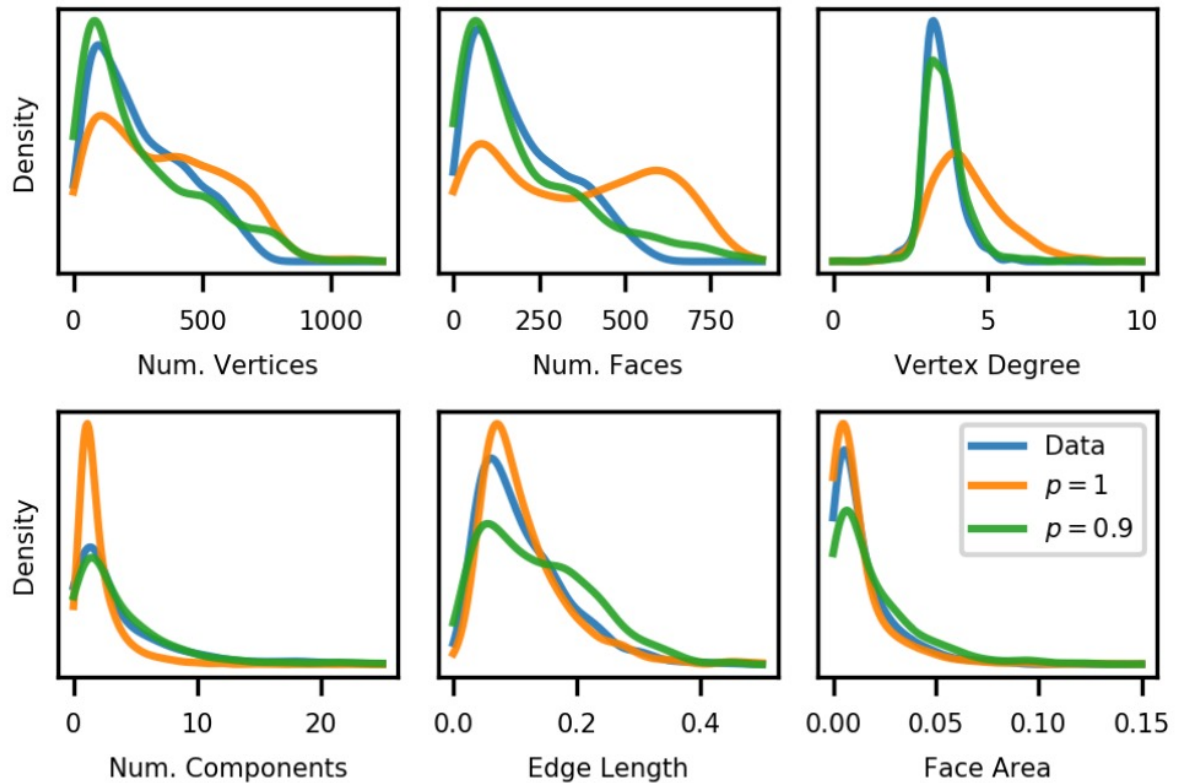
Symmetric Chamfer Distance between two point sets

$$\mathcal{L}(\mathcal{P}, \mathcal{Q}) = \sum_{\mathbf{p} \in \mathcal{P}} \min_{\mathbf{q} \in \mathcal{Q}} (\mathbf{p} - \mathbf{q})^2 + \sum_{\mathbf{q} \in \mathcal{Q}} \min_{\mathbf{p} \in \mathcal{P}} (\mathbf{p} - \mathbf{q})^2$$



Experimental Results

- But are the meshes any good?
- Some crude statistics...
- Blue line is ground truth from ShapeNet



Critique / Limitations / Open Issues

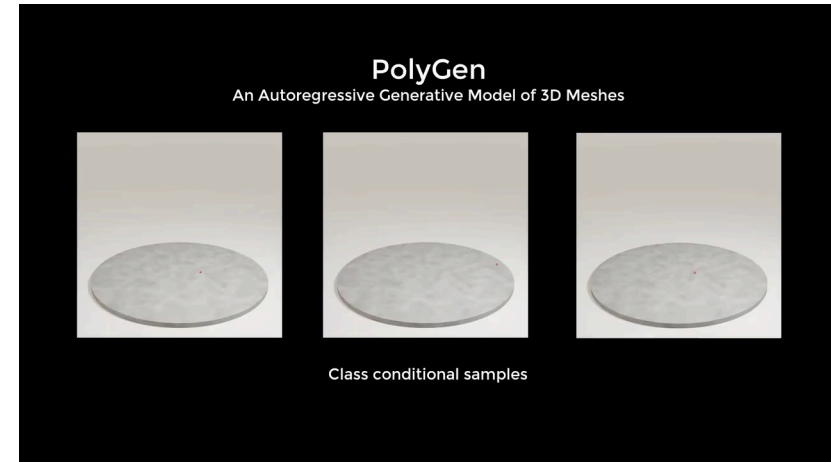
- Transformers are expensive to train
 - Attention is quadratic in nature $O(L^2)$
 - New mechanism is $O(L \log(L))$! <Reformer: The efficient Transformer>
 - Can limit mesh sizes (Scalability <vertex history>)
 - Don't know what the limits are... not in paper, or code...
 - Quantization hides some of this
 - Need better quality metrics for understanding statistical variations
- Rotations
- Unclear on performance with generalized curvature
- No new benchmark metrics (yet)...
- Generation could be slow since it's sequential
- Non-planar n-gons (probably filtered out organic/curvy things!)
- Low res 256x256x256 mesh/voxel coords.



Contributions recap



- First: Unconditional mesh vertex & face models create polygon meshes!
- Demonstrated conditional generation given
 - Object Class
 - Image
 - Voxels
- Novel application of Transformers to Meshes
 - vertex & face distributions, robust to bad input
- Output is diverse, realistic and directly usable in graphics applications – unlike previous post-processed output



Thank You!

